



ECET 4530

Industrial Motor Control

Directional Control of 3 Φ Induction Motors

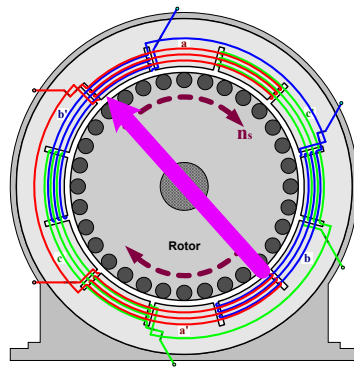
1



Rotational Direction of a 3 Φ Motor

When supplied with a balanced set of three-phase voltages, the **stator windings** of a 3 Φ Induction Motor produce a **rotating magnetic field** that passes through the machine's rotor region.

The stator construction shown is that for a 2-pole motor, such that it contains one set of three-phase windings that are symmetrically-placed around the stator.



The speed at which the field rotates is referred to as the synchronous speed (n_s) of the motor and is a function of both the number of poles and the frequency of the voltages:

$$n_s = \frac{120 \cdot f_{elec}}{\# \text{ poles}}$$

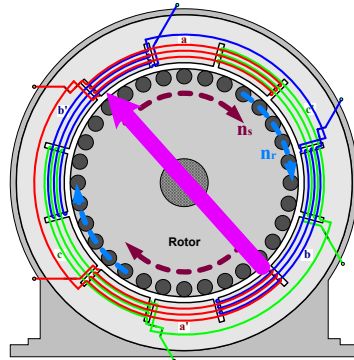
2



Rotational Direction of a 3 Φ Motor

The **rotating stator field** induces a torque upon the rotor that tries to **accelerate the rotor in the same direction as the rotating field**.

Thus, the **rotational direction** of a 3 Φ Induction Motor is determined by the **rotational direction of its stator field**.



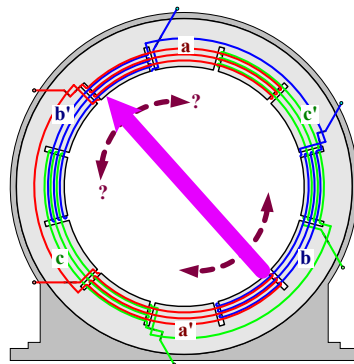
3



Rotational Direction of a 3 Φ Motor

But the **rotational direction** of its stator field is affected by both:

- the **layout of the stator windings**, and
- the **phase sequence of the voltages** supplying those windings.



The windings shown are laid-out such that *winding-b* is rotated 120° CW from *winding-a*, and *winding-c* is rotated 120° CW from *winding-b*.

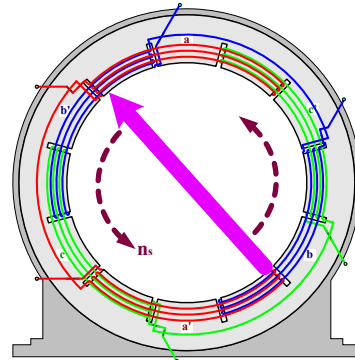
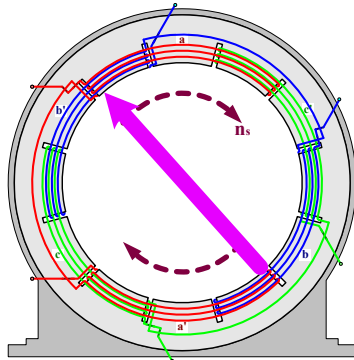
4



Rotational Direction of a 3 Φ Motor

For example, with the windings oriented as shown, the field will:

- rotate clockwise when supplied by a **positive-sequence** set of three-phase voltages.
- rotate counter-clockwise when supplied by a **negative-sequence** set of three-phase voltages.

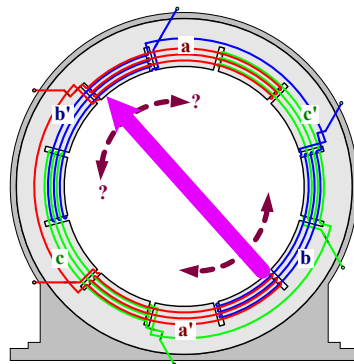


5



Rotational Direction of a 3 Φ Motor

Thus, given a 3 Φ Induction Motor, the windings of which have been configured in a specific manner, it is the **phase sequence** of the supply voltage that **determines the motor's direction of rotation**.

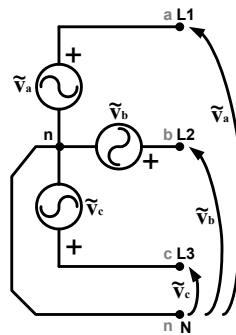


6



Phase Sequence

The **phase sequence** of a 3 Φ supply is determined by the specific relationship between the phase angles of the supply's individual phase voltages (or line voltages).



Phase Voltages of a Y-connected 3 Φ Supply

7

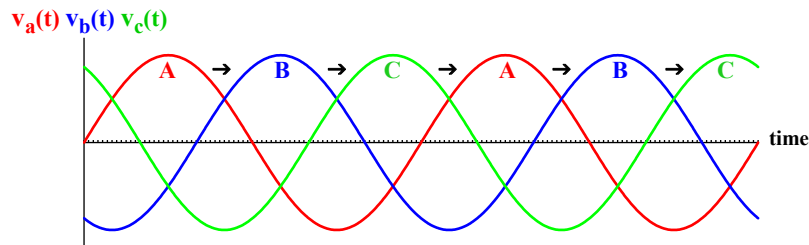


Positive Phase-Sequence

The **phase sequence** of a 3 Φ supply is determined by the specific relationship between the phase angles of the supply's individual phase voltages (or line voltages).

A **positive-sequence** supply is defined such that its phase **A** voltage **leads** its phase **B** voltage by 120°, and its phase **B** voltage leads its phase **C** by 120°.

$$\begin{aligned} \tilde{V}_a &= V \angle \phi \\ \tilde{V}_b &= V \angle \phi - 120^\circ \\ \tilde{V}_c &= V \angle \phi - 240^\circ \end{aligned}$$



8

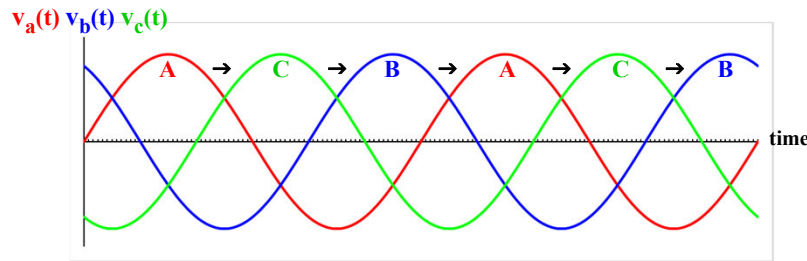


Negative Phase Sequence

The **phase sequence** of a 3 Φ supply is determined by the specific relationship between the phase angles of the supply's individual phase voltages (or line voltages).

A **negative-sequence** supply is defined such that its phase **A** voltage **lags** its phase **B** voltage by 120°, and its phase **B** voltage **lags** its phase **C** by 120°.

$$\begin{aligned}\tilde{V}_a &= V \angle \phi \\ \tilde{V}_b &= V \angle \phi + 120^\circ \\ \tilde{V}_c &= V \angle \phi + 240^\circ\end{aligned}$$



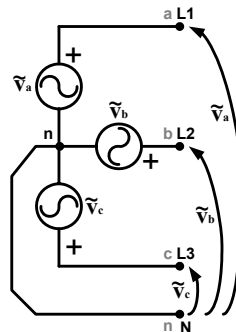
↑
increasing angles

9



Phase Sequence from a Supply Panel

The actual **phase sequence** of a 3 Φ supply is hard-wired into an electrical distribution system, such that the voltages available from line-terminals L1, L2, and L3 of an electrical supply panel will either have a positive or a negative sequence, and this cannot be changed without rewiring the supply panel.



Phase Voltages of a Y-connected 3 Φ Supply

10



Comparing the Phase Sequences

But note that phase voltage V_b of a positive-sequence supply is equivalent to voltage V_c of a negative-sequence supply, and that phase voltage V_c of a positive-sequence supply is equivalent to voltage V_b of a negative-sequence supply:

Positive-Sequence

$$\tilde{V}_a = V \angle \phi$$

$$\tilde{V}_b = V \angle \phi - 120^\circ$$

$$\tilde{V}_c = V \angle \phi - 240^\circ$$

Negative-Sequence

$$\tilde{V}_a = V \angle \phi$$

$$\tilde{V}_b = V \angle \phi + 120^\circ$$

$$\tilde{V}_c = V \angle \phi + 240^\circ$$



This occurs because rotating 120° CW on a polar plot (subtracting 120°) is equivalent to rotating 240° CCW on a polar plot (adding 240°), and vice-versa.

$$V \angle \phi - 120^\circ = V \angle \phi + 240^\circ$$

11



Reversing the Phase Sequence

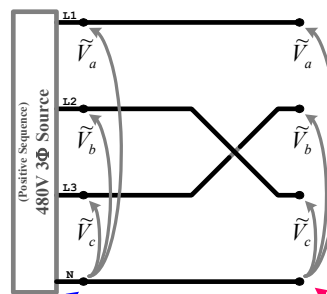
Thus, if a **positive-sequence** set of voltages are available at the terminals of a supply panel, then those voltages can effectively be converted to a negative-sequence set of voltages by **swapping lines B & C** (or any other pair of supply lines) when pulling lines from the panel:

$$\tilde{V}_a = V \angle \phi$$

$$\tilde{V}_b = V \angle \phi - 120^\circ$$

$$\tilde{V}_c = V \angle \phi - 240^\circ$$

Positive-sequence voltages at supply-panel terminals.



$$\tilde{V}_a = V \angle \phi$$

$$\tilde{V}_b = V \angle \phi + 120^\circ$$

$$\tilde{V}_c = V \angle \phi + 240^\circ$$

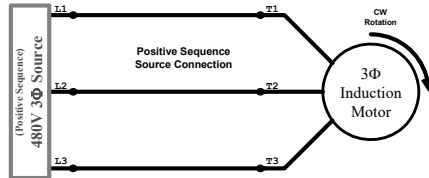
Negative-sequence voltages available at wired-ends.

12



Reversing the Direction of a Motor

Based on this concept, given the following **positive-sequence** source supplying a 3 Φ Induction Motor that rotates in the **CW direction**:



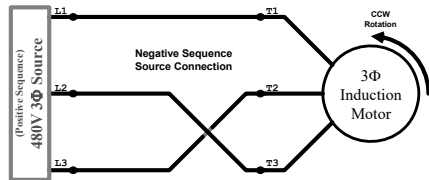
$$\tilde{V}_a = V \angle \phi$$

$$\tilde{V}_b = V \angle \phi - 120^\circ$$

$$\tilde{V}_c = V \angle \phi - 240^\circ$$

Voltages
seen at
the motor's
terminals.

the **direction** of rotation can be reversed by **swapping lines B & C**.



$$\tilde{V}_a = V \angle \phi$$

$$\tilde{V}_b = V \angle \phi + 120^\circ$$

$$\tilde{V}_c = V \angle \phi + 240^\circ$$

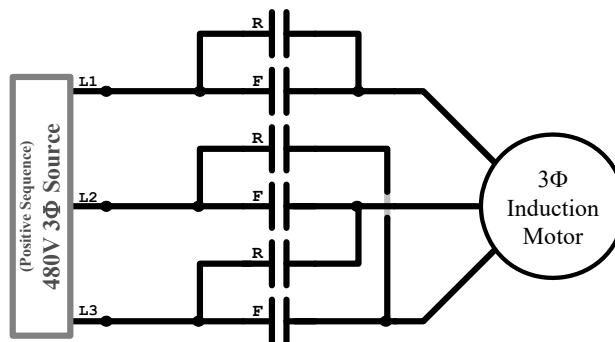
Voltages
seen at
the motor's
terminals.

13



Directional Control of a 3 Φ Motor

Directional control of a 3 Φ Induction Motor can be achieved by using two main contactors; **one to supply a positive-sequence set of voltages** to the motor, and **the other to supply the motor with a set of negative-sequence voltages** (i.e. – swap two lines).

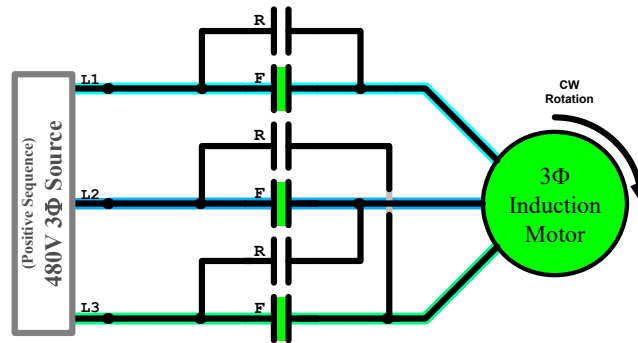


14



Forward Operation

When the “**F**” (**F**orward) contactor’s **field coil is energized**, its main contacts will actuate (close), in-turn **supplying** the 3 Φ Induction Motor with a **positive-sequence** set of voltages and causing the motor to rotate in the **CW direction**.



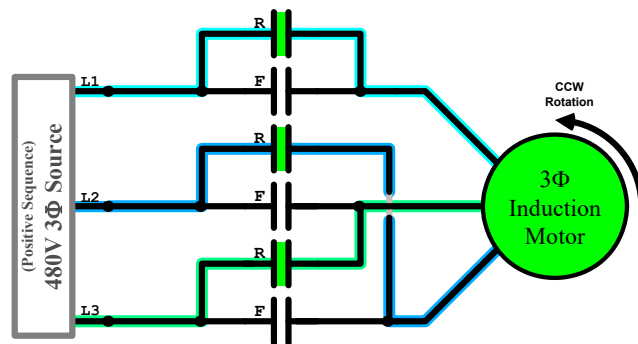
Assuming that the motor will rotate in the CW direction for a positive-sequence supply voltage...

15



Reverse Operation

When the “**R**” (**R**everse) contactor’s **field coil is energized**, its main contacts will actuate (close), in-turn **supplying** the 3 Φ Induction Motor with a **negative-sequence** set of voltages and causing the motor to rotate in the **CCW direction**.



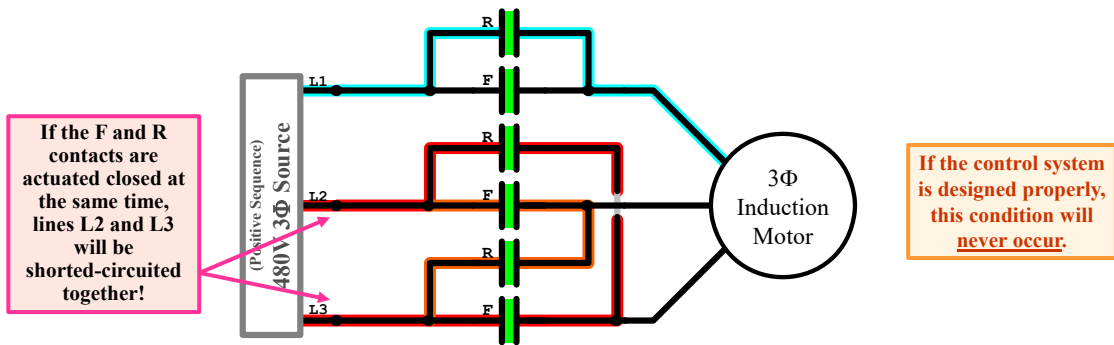
Assuming that the motor will rotate in the CW direction for a positive-sequence supply voltage, then a negative-sequence supply will cause it to rotate in the CCW direction.

16



Dangerous Operating Condition!

When using one contactor to energize the motor in the forward direction and a second to energize the motor in the reverse direction, **extreme care** must be taken to **ensure that both sets of contacts (F and R) are never actuated at the same time!**



17

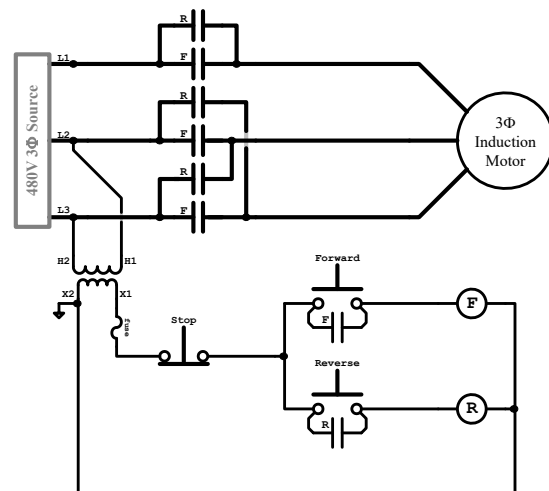


Directional Control of a 3Φ Motor

The figure shown to the right includes the components that are required to **control** the Forward and Reverse contactors.

Although a **single stop button** is utilized, **two start buttons** are required:

- one to **start** the motor in the **forward** direction, and
- the other to **start** the motor in the **reverse** direction.



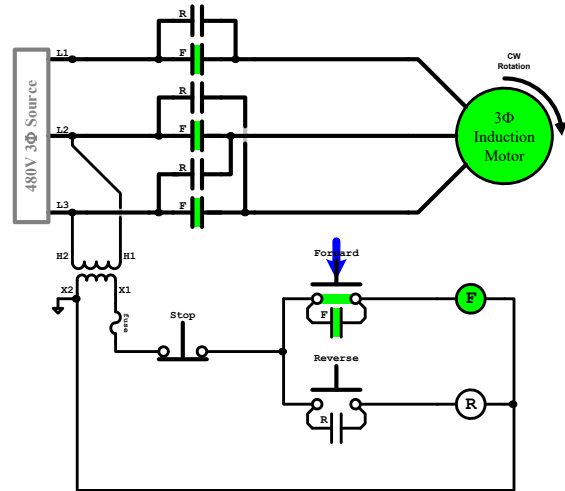
18



Forward Operation

When the “Forward” button is pressed:

- the **F field coil** (Forward contactor) is **energized**, actuating the **F contacts closed**, and
- when the **F contacts close**, the motor is supplied with a **positive-sequence** set of voltages and causing the motor to rotate in the **CW** direction.



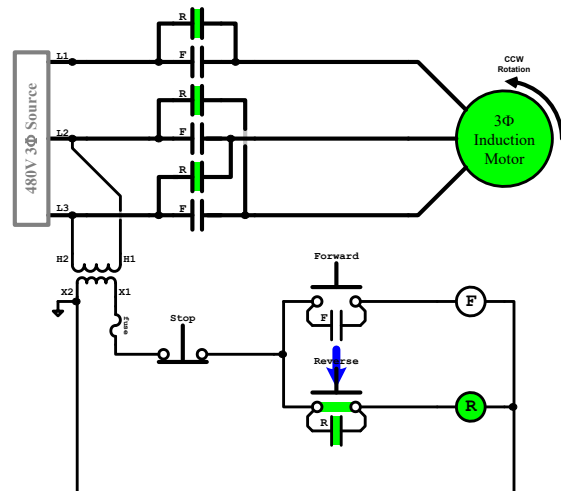
19



Reverse Operation

Or, when then the “Reverse” button is pressed:

- the **R field coil** (Reverse contactor) is **energized**, actuating the **R contacts closed**, and
- when the **R contacts close**, the motor is supplied with a **negative-sequence** set of voltages and causing the motor to rotate in the **CCW** direction.



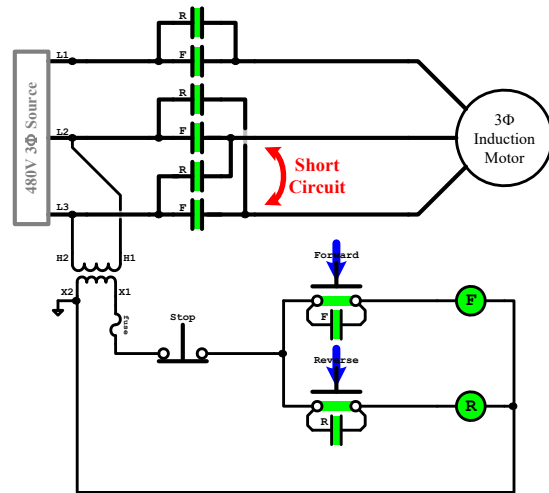
20



Dangerous Operational State!!!

Note that, as shown, both the **Forward** and the **Reverse** field coils can be energized **simultaneously**.

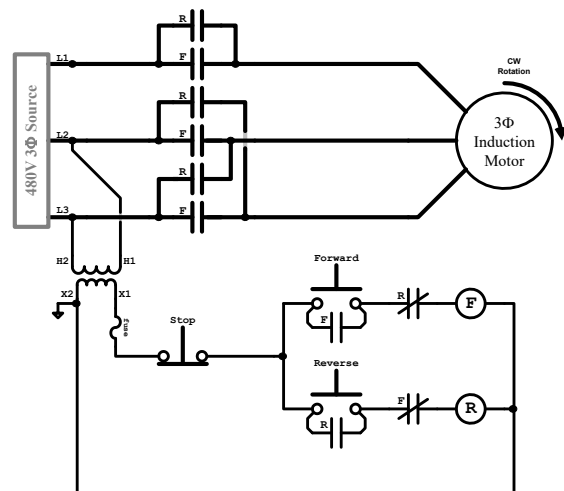
If this occurs, the **F** and **R** contacts will all **actuate** closed, in-turn creating a **short-circuit** current path between supply lines **B & C**.



21

Designing for Safe Operation

To prevent one field coil from becoming energized after the other is already energized, a pair of opposing **NC** contacts can be **placed in series** with each of the field coils.



22

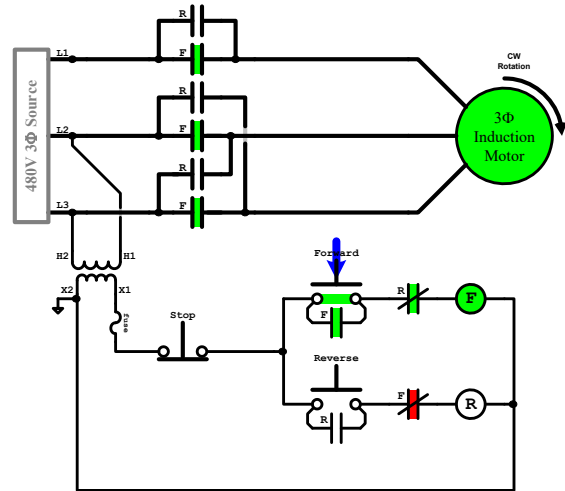


Designing for Safe Operation

To prevent one field coil from becoming energized after the other is already energized, a pair of opposing NC contacts can be placed in series with each of the field coils.

If one field coil is energized, that field coil's NC contact will actuate (open), in-turn preventing the other field coil from being energized.

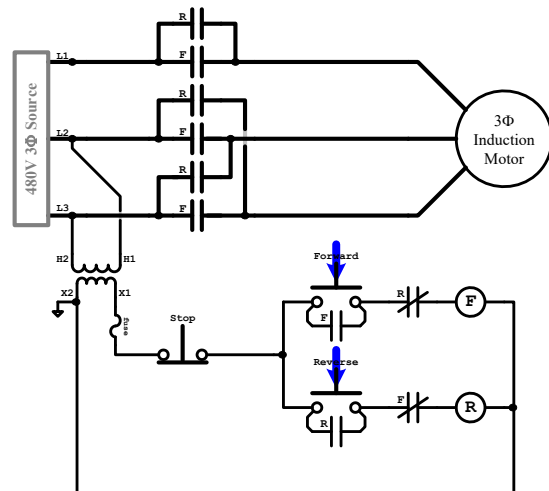
Will this always prevent a short-circuit condition?



23

Designing for Safe Operation

Although the addition of the opposing NC contacts will prevent a second field coil from being energized after the motor is started in one direction, this does **not** account for the **simultaneous** pressing of both the Forward and the Reverse buttons.



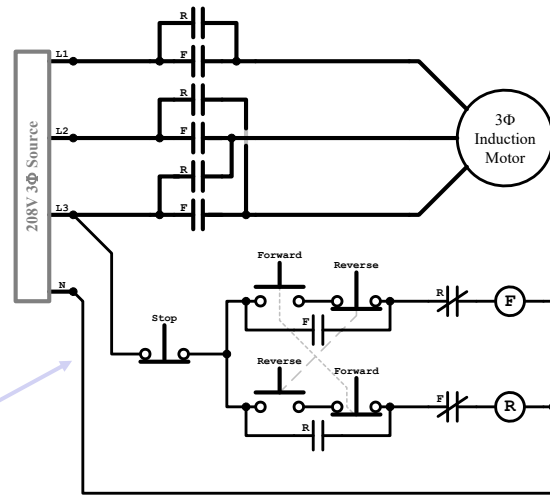
24



Designing for Safe Operation

Combination pushbuttons can be utilized in order to provide the necessary protection that will prevent both field coils from being energized if the **Forward** and **Reverse** buttons are pressed simultaneously.

Note that the control circuit in this figure is shown to be connected directly across one phase of a 208V 3 Φ source instead of using a transformer to step-down the voltage from a 480V 3 Φ source. This change was made to both simplify the figure and to better represent the circuit that would be constructed in the Q-215 lab.

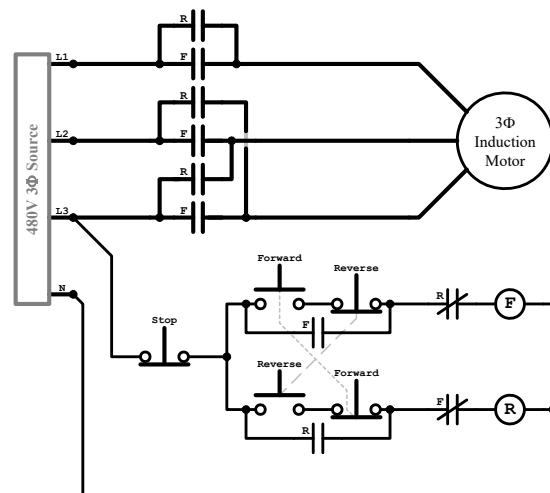


25



Designing for Safe Operation

Note that there are also special “**Reversing-Contactors**” available that effectively contain individual two contactors along with an interlock that will physically prevent both armatures from actuating simultaneously.



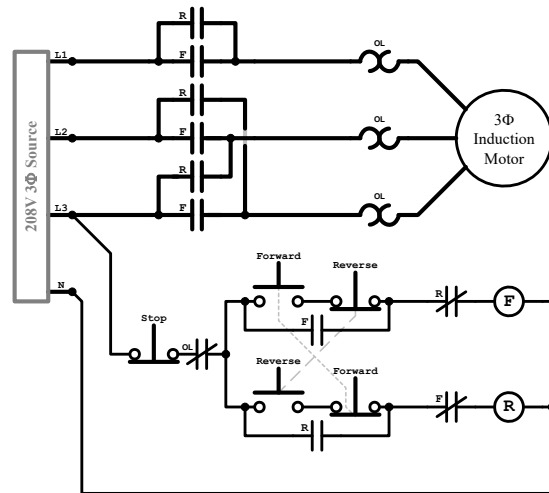
26



Forward/Reverse Motor Starter

One typical component of a **motor starter** that has been missing up to this point is **overload protection**.

To add overload protection, the **OL relay's NC contact** must be placed in **series** with the **Stop** button in order for the OL relay to be able to de-energize whichever field coil had been energized.



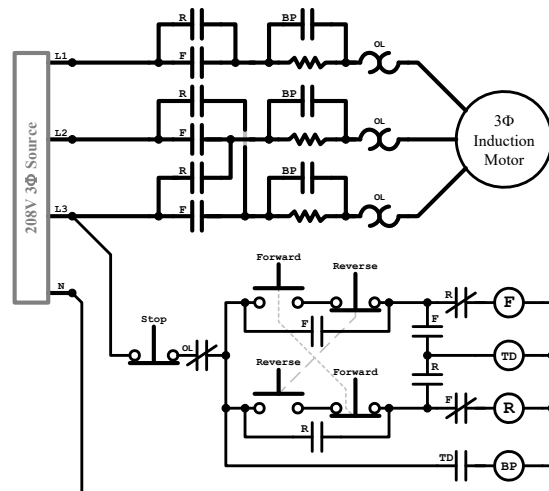
27



Reduced-Voltage Starter w/ Directional Control

Finally, what if the motor needs to be **soft-started**?

A series-resistance, reduced-voltage starting scheme can be employed.



28