

3Φ INDUCTION MACHINES

**Problem #1)** A 3Φ, 60 Hz, design B, 100 hp, squirrel cage induction motor has a rated operating speed of 870 rpm. Determine the **number of poles** of the machine.

$$\# \text{ poles} = \underline{\quad 8 \quad} \text{ poles}$$

**Problem #2)** Given a 4 pole, 50 hp, 1755 rpm, 460 V, 60 Hz, squirrel cage induction machine, determine the rated **Torque** of the machine in lb·ft.

$$T = \underline{\quad 149.6 \quad} \text{ lb}\cdot\text{ft}$$

**Problem #3)** A 1 hp, 48 pole, 50 Hz, induction motor is operating at a speed of 120 rpm. Determine the **slip** at this speed.

$$s = \underline{\quad 4 \quad} \%$$

**Problem #4)** Briefly describe the operational mechanism that causes an induction machine to develop no torque when operating at its synchronous speed.

*The rotor conductors are rotating at the same speed of the stator field  $\Rightarrow$  no voltage is induced on the conductors.*

**Problem #5)** Given a 3Φ, 40-hp, 460-V, 4-pole, 60 Hz, Y-connected, squirrel-cage, induction machine with the following characteristics:

$$R_S = 0.1 \, \Omega, \quad X_S = 0.4 \, \Omega, \quad R'_R = 0.15 \, \Omega, \quad X'_R = 0.6 \, \Omega,$$

$$R_{fe} = 102 \, \Omega, \quad X_m = 7.7 \, \Omega, \quad P_{\text{mechlosses}} = 1200 \text{ W}.$$

If the machine is operating at rated voltage and a slip of 2%, determine the **input current magnitude** and the **power on the shaft** of the machine.

$$|I_{\text{line}}| = \underline{\quad 53.73 \quad} \text{ A}$$

$$P_{\text{shaft}} = \underline{\quad 33.87 \quad} \text{ hp}$$

**Problem #6)** Given a 6 pole, 50 hp, 1155 rpm, 460 V, 60 Hz, squirrel cage induction machine, determine the rated **Torque** of the machine in lb.-ft.

$$T_{\text{rated}} = \underline{\quad 227.36 \quad} \text{ lb}\cdot\text{ft}$$

**Problem #7)** A 1 hp, 48 pole, 50 Hz, induction motor is operating at a slip of 3.2%. Determine the **speed** of the machine.

$$n_r = \underline{\quad 121 \quad} \text{ rpm}$$

**Problem #8)** Given a 3Φ, 80-hp, 460-V, 4-pole, 60 Hz, Y-connected, squirrel-cage, induction machine with the following characteristics:

$$R_S = 0.2 \, \Omega, \quad X_S = 0.4 \, \Omega, \quad R'_R = 0.2 \, \Omega, \quad X'_R = 0.6 \, \Omega,$$

$$R_{fe} = 102 \, \Omega, \quad X_m = 7.7 \, \Omega.$$

If the machine is operating at 70% of rated load and a slip of 5%, determine the **total mechanical losses** of the machine.

$$P_{\text{mechlosses}} = \underline{\quad 1361 \quad} \text{ W}$$

**Problem #9)** A 3Φ, 60Hz, 50 hp, squirrel cage induction motor has a rated operating speed of 1165 rpm. Determine the **number of poles** of the machine.

$$\# \text{ poles} = \underline{\quad 6 \quad} \text{ poles}$$

**Problem #10)** Given a 3 $\Phi$ , 40-hp, 460-V, 4-pole, 60 Hz, Y-connected, squirrel-cage, induction machine with the following characteristics:  $R_S = 0.15 \Omega$ ,  $X_S = 0.5 \Omega$ ,  $R'_R = 0.15 \Omega$ ,  $X'_R = 0.6 \Omega$ ,

$$R_{fe} = 102 \Omega, \quad X_m = 7.7 \Omega.$$

If the machine is operating at rated voltage and a speed of 1728 rpm, determine the **torque** developed by the machine and the **input impedance** of the machine.

$$T_D = \underline{\quad 189.0 \quad} \text{ lb}\cdot\text{ft}$$

$$Z_{in} = \underline{\quad 2.475 + j1.97 \quad} \Omega$$

**Problem #11)** Which Induction machine circuit-model **parameters** are determined from the **Blocked Rotor Test**? (Be specific – Do not assume that any other tests are also being performed on the machine.)

$$R_{eq} \text{ and } X_{eq}$$

**Problem #12)** A 1/2-hp, 4-pole, 60-Hz, 1740-rpm induction motor is 74% efficient at rated load. Determine the **electrical input power** under rated conditions.

$$\text{For motor: } \eta = \frac{P_{out}}{P_{in}} = \frac{P_{shaft}}{P_{elec}} \quad \therefore \quad P_{elec} = \frac{P_{shaft}}{\eta} = \frac{1/2 \text{ hp} \cdot 746 (\text{W}/\text{hp})}{0.74} = 504 \quad P_{in} = \underline{\quad 504 \quad} \text{ W}$$

**Problem #14)** A 3 $\Phi$ , 60Hz, design B, 15-hp, squirrel cage induction motor has a rated speed of 700 rpm. Determine the **number of poles** of the machine.

$$\# \text{ poles} = \underline{\quad 10 \quad} \text{ poles}$$

**Problem #15)** A 4 pole, 230V, 60Hz, induction motor is operating with a slip of 4%. Determine the **speed**.

$$n_r = \underline{\quad 1728 \quad} \text{ rpm}$$

**Problem #16)** Given a 3 $\Phi$ , 40-hp, 460-V, 8-pole, 60 Hz, Y-connected, squirrel-cage, induction machine with the following characteristics:  $R_s = 0.15 \Omega$ ,  $X_s = 0.5 \Omega$ ,  $R'_r = 0.2 \Omega$ ,  $X'_r = 0.5 \Omega$ ,  $R_{fe} = 102 \Omega$ ,  $X_m = 7.7 \Omega$ .

If the machine is operating at rated voltage and a speed of 885 rpm, determine the **torque** developed by the machine.

$$\text{Note: } T_D = T_{mech}$$

$$T_D = \underline{\quad 133.64 \quad} \text{ lb}\cdot\text{ft}$$

**Problem #17)** Given a 3 $\Phi$ , 50-hp, 460V, 6-pole, 1142 rpm, 60Hz, squirrel-cage, induction machine: Determine the **rated torque** of the machine.

$$T_{rated} = \underline{\quad 229.95 \quad} \text{ lb}\cdot\text{ft}$$

**Problem #19)** A 12 pole, 50 Hz, induction motor is operating at a slip of 2%. Determine the machine's **speed**.

$$n_r = \underline{\quad 490 \quad} \text{ rpm}$$

**Problem #20)** Given a 3 $\Phi$ , 40-hp, 460-V, 8-pole, 60 Hz, Y-connected, squirrel-cage, induction machine with the following characteristics:  $R_s = 0.2 \Omega$ ,  $X_s = 0.5 \Omega$ ,  $R'_r = 0.16 \Omega$ ,  $X'_r = 0.6 \Omega$ ,  $R_{fe} = 100 \Omega$ ,  $X_m = 8 \Omega$ .

If the machine is operating at rated voltage and a speed of 880 rpm, determine the **magnitude of the line current** and the **developed (mechanical) torque** for the machine.

$$I_{line} = \underline{\quad 53.87 \quad} \text{ A}$$

$$T_{mech} = \underline{\quad 212.93 \quad} \text{ lb}\cdot\text{ft}$$

(Theory Questions Relating to Induction Machines)

Problem #21) Define the term *synchronous speed* with respect to induction machines.

- i – the rotational speed of the stator field, or*
- ii – the speed at which the machine develops no torque*

Problem #22) For each of the following statements, specify whether they are **TRUE** or **FALSE**.

- False** A 3- $\Phi$  induction machine produces *no developed torque at start-up* (startup:  $n_r = 0$ ).
- True** A 3- $\Phi$  induction machine produces *no mechanical power at start-up*.
- False** The *breakdown torque* for a 3 $\Phi$  induction machine is the maximum load torque that the machine is able to break-free and accelerate at start-up.
- True** The *no-load test* for a 3 $\Phi$  induction machine allows for solution of the excitation impedances in the equivalent circuit model.
- True** The *rated speed* of a 3 $\Phi$  induction machine is the speed the machine should run under full-rated conditions.
- True** A 3 $\Phi$ , squirrel-cage, induction machine requires *no external electrical connection to the rotor*.
- True** A 4-pole, 3 $\Phi$  induction machine will have a *higher synchronous speed* when supplied by a 60Hz source compared to when being supplied by a 50Hz source.
- True** A 3 $\Phi$  induction machine produces *no developed (mechanical) torque at synchronous speed*.
- True** A 3 $\Phi$  induction machine produces *no torque* and *no mechanical power* at synchronous speed.
- True** The *direction of rotation* for a 3 $\Phi$  induction machine depends on the phase sequence of the source.
- False** At synchronous speed, a 3 $\Phi$  induction machine will draw *no line current* ( $I_{line} = 0A$ ).
- False** The *frequency of the rotor voltages* in a 3 $\Phi$  induction machine will increase as the machine accelerates from start-up to synchronous speed.
- True** 1 *horsepower* is roughly equivalent to 746 watts of power.
- False** A 3 $\Phi$  induction machine functions as a *generator when running backwards*.
- True** The *rated speed* of a 3 $\Phi$  induction machine is the speed the machine should run under full-rated conditions.
- False** Increasing the *rotor-circuit resistance* of a 3 $\Phi$ , wound-rotor induction machine will increase the speed at which maximum torque occurs.
- False** When supplied at rated voltage, a 3 $\Phi$  induction machine develops *rated torque* at its synchronous speed.
- False** The “no-load” speed of an “ideal” 3 $\Phi$  induction motor can be increased by increasing the *magnitude* of its supply voltage.

**Problem #23)** A 15hp, 230V, 1750rpm, DC shunt-motor has field and armature resistances of  $140\Omega$  and  $0.3\Omega$  respectively. If the motor draws a line current of 55A under full rated conditions, determine:

- The full-voltage start-up terminal current if no external starting resistance is applied.
- The full-voltage start-up terminal current if a  $5\Omega$  resistor is connected in series with the armature circuit.

a)  $I_{\text{start}(R=0\Omega)} = \underline{768.3} \text{ A}$

b)  $I_{\text{start}(R=5\Omega)} = \underline{45.0} \text{ A}$

**Problem #24)** A 25hp, 240V, DC shunt-motor ( $R_f = 120\Omega$ ,  $R_a = 0.25\Omega$ ) draws 90A when supplied with rated voltage and driving *rated load*. Determine the **mechanical losses** experienced by the motor.

$P_{\text{mech.losses}} = \underline{537} \text{ W}$

**Problem #25)** A 30hp, 240V, shunt-excited DC motor running at 900 rpm draws a line current of 90A when supplied at rated voltage and driving a constant-torque (*not-rated*) load. The respective field and armature resistances are  $120\Omega$  and  $0.25\Omega$ . Neglecting any mechanical losses in the machine:

- Determine the **mechanical power** produced by the machine.
- If a resistor is placed in series with the field winding that decreases the pole flux by 25%, determine the new operating **speed** of the motor.

a)  $P_{\text{mech}} = \underline{25.7} \text{ hp}$

b)  $n_{\text{new}} = \underline{1160} \text{ rpm}$

**Problem #26)** A 240V, shunt-excited DC motor running at 900 rpm draws a line current of 90A at rated voltage when supplied at rated voltage and driving a load. The respective field and armature resistances are  $120\Omega$  and  $0.3\Omega$ . Neglecting any mechanical losses in the machine:

- Determine the **mechanical power** produced by the machine
- If a change in the motor's mechanical load causes the input current to increase by 10%, determine the *new mechanical power* and the *new speed* of the motor.

a)  $P_{\text{mech}} = \underline{25.2} \text{ hp}$

b)  $P_{\text{mech}} = \underline{27.4} \text{ hp}$

$n_{\text{new}} = \underline{888.6} \text{ rpm}$

**Problem #27)** A 240V, DC shunt-motor ( $R_f = 120\Omega$ ,  $R_a = 0.3\Omega$ ) draws 90A and rotates at 900rpm when driving a constant-torque (*non-rated*) load and supplied at rated voltage. If a  $1\Omega$  resistor is placed in series with the armature circuit, determine the *new speed* of the motor along with the *mechanical power* produced by the motor (with the resistor in place).

$n_{\text{new}} = \underline{529} \text{ rpm}$

$P_{\text{mech}} = \underline{14.8} \text{ hp}$

- Problem #28)** Given a 120V, ½hp, **series**-excited, DC motor with field resistance of 3.4Ω and an armature resistance of 2.6Ω; Assuming that the total pole flux created by the motor is linearly proportional to the motor’s field current ( $\Phi \equiv I_f$ ) and that the motor is supplied at rated voltage:
- If the motor draws a terminal current of 1.5A while rotating at a speed of 1600rpm, determine the total **torque**,  $T_D$ , developed by the motor at this operating point.
  - If the load torque increases such that the motor draws a 3x larger terminal current of 4.5A, determine the **new operational speed** and the **new torque** developed by the motor.

$V_t = 120V$  (for parts “a” and “b”)

Part “a”

$$I_{t(\text{orig})} = 1.5A$$

$$E_{a(\text{orig})} = 111V$$

$$P_{\text{mech}(\text{orig})} = 166.5W = 0.2232\text{hp}$$

$$T_{D(\text{orig})} = \mathbf{0.7326\text{lb}\cdot\text{ft}}$$

$$(k_G\Phi)_{\text{orig}} = 0.069375$$

Part “b”

$$I_{t(\text{new})} = 4.5A$$

$$E_{a(\text{new})} = 93V$$

$$P_{\text{mech}(\text{new})} = 418.5W = 0.5610\text{hp}$$

$$(k_G\Phi)_{\text{new}} = 0.208125$$

$$n_{\text{new}} = \mathbf{447\text{rpm}}$$

$$T_{D(\text{new})} = \mathbf{6.594\text{lb}\cdot\text{ft}}$$

$$\text{a) } T_D = \underline{\mathbf{0.7326}} \text{ lb}\cdot\text{ft}$$

$$\text{b) } n_{(\text{new})} = \underline{\mathbf{447}} \text{ rpm}$$

$$T_{D(\text{new})} = \underline{\mathbf{6.594}} \text{ lb}\cdot\text{ft}$$

- Problem #29)** Given a 5hp, 1800rpm, 230V<sub>DC</sub>, shunt-excited motor with circuit model resistances:

$$R_f = 209\Omega, \quad R_a = 1.5\Omega \quad (\text{Assume } P_{\text{mech.losses}} = 0W)$$

- Determine the **rated torque**,  $T_{\text{shaft}(\text{rated})}$ , for the motor in lb·ft.
- If the motor draws a terminal current of 14.3A while supplied with rated voltage but driving **less-than-rated** load, determine the **mechanical power**,  $P_{\text{mech}}$ , produced by the motor in horsepower and the operational **efficiency**,  $\eta$ , of the motor in percent.
- Determine the **starting current** for the motor if it is initially started by applying full (rated) terminal voltage. (Note – “starting” condition  $\rightarrow n_r = 0$  rpm)

$$\text{a) } T_{\text{shaft}(\text{rated})} = \underline{\mathbf{14.6}} \text{ lb}\cdot\text{ft}$$

(see last page for solution)

$$\text{b) } P_{\text{mech}} = \underline{\mathbf{3.72}} \text{ hp}$$

$$\eta = \underline{\mathbf{84.4}} \%$$

$$\text{c) } I_{t(\text{starting})} = \underline{\mathbf{154.4}} \text{ A}$$

- Problem #30)** A 12V, permanent-magnet DC motor (no field winding) with an armature circuit resistance  $R_a = 4\Omega$  is used to drive a radio-controlled car. The motor rotates at a speed of 2700rpm and draws a terminal current  $I_t = 300\text{mA}$  when the car is traveling on a smooth, level surface. Assuming that the motor is supplied at rated voltage:

- Determine the **torque** that the motor develops,  $T_D$ , in lb·ft when on the level surface.
- When the car begins traveling up a long incline, the car’s speed decreases and the motor’s terminal current increases to  $I_t = 500\text{mA}$ . Determine new **torque** developed by the motor,  $T_{D(\text{incline})}$ , in lb·ft and the new rotational **speed** of the motor,  $n_{r(\text{incline})}$ , in rpm.

$$\text{a) } T_D = \underline{\mathbf{0.0084448}} \text{ lb}\cdot\text{ft}$$

(see last page for worked-out solution)

$$\text{b) } T_{D(\text{incline})} = \underline{\mathbf{0.01408}} \text{ lb}\cdot\text{ft}$$

$$n_{\text{new}(\text{incline})} = \underline{\mathbf{2500}} \text{ rpm}$$

**Problem #31)** Given a small  $18V_{DC}$  permanent-magnet motor with armature circuit resistance  $R_a=2\Omega$ ; While the motor is supplied with rated voltage and driving a small load, the motor's speed was measured at 2670rpm and the terminal current was measured at 0.4A.

- a) Determine the **torque**,  $T_{D(2670)}$ , developed by the motor while operating as specified above.
- b) An increase in load torque causes the motor to slow down to 2150rpm while still supplied at rated voltage. Determine the **new terminal current**,  $I_t(2150)$ , and the **new torque**,  $T_{D(2150)}$ , developed by the motor while rotating at 2150rpm.
- c) If the permanent magnets that provide the stator flux are swapped-out with rare-earth magnets that provide 2x more flux than the original magnets, determine the **new rotational speed** of the motor,  $n_r$ , assuming that the motor is developing the same torque as in part (b).

$$\text{a) } T_{D(2670)} = \underline{\quad \mathbf{0.01814} \quad} \text{ lb}\cdot\text{ft}$$

$$\text{b) } I_t = \underline{\quad \mathbf{2.075} \quad} \text{ A}$$

$$T_{D(2150)} = \underline{\quad \mathbf{0.0941} \quad} \text{ lb}\cdot\text{ft}$$

$$\text{c) } n_r = \underline{\quad \mathbf{1236} \quad} \text{ rpm}$$

**Problem #32)** Given the permanent-magnet motor from problem #31 ( $18V_{DC}$ ,  $R_a=2\Omega$ ) supplied at 18V:

- a) Determine the value of the **terminal current** that the motor will draw and the **torque** that the motor will develop at start-up with the original magnets in place.
- b) Determine the value of the **terminal current** that the motor will draw and the **torque** that the motor will develop at start-up with the rare-earth magnets in place.

$$\text{a) } I_t = \underline{\quad \mathbf{9} \quad} \text{ A}$$

$$T_D = \underline{\quad \mathbf{0.408} \quad} \text{ lb}\cdot\text{ft}$$

$$\text{b) } I_t = \underline{\quad \mathbf{9} \quad} \text{ A}$$

$$T_D = \underline{\quad \mathbf{0.816} \quad} \text{ lb}\cdot\text{ft}$$

**Problem #33)** Write **True** or **False** in each blank based upon the validity of each statement:

- False A 3 $\Phi$  induction machine develops no torque at start-up.
- True A 3 $\Phi$  induction machine produces no mechanical power at start-up (when  $n_r = 0$ ).
- False The breakdown torque for a 3 $\Phi$  induction machine is the maximum torque load the machine is able to break-free and accelerate at start-up.
- True The rated speed of a 3 $\Phi$  induction machine is the speed the machine should run under full-rated conditions.
- True A 3 $\Phi$ , squirrel-cage, induction machine requires no external electrical connection to the rotor.
- True A 4-pole, 3 $\Phi$  induction machine will have a higher synchronous speed when supplied by a 60Hz source compared to when being supplied by a 50Hz source.
- True A 3- $\Phi$  induction machine produces no torque or mechanical power at synchronous speed.
- True The direction of operation for a 3 $\Phi$  induction machine depends on the phase sequence of the voltage source.
- False At synchronous speed, a practical 3 $\Phi$  induction machine will draw no line current ( $I_{line} = 0A$ ).
- True 1 horse power is roughly equivalent to 746 watts of power.
- False Increasing the field current in a shunt-excited DC motor will typically cause an increase in speed.
- False When supplied at rated voltage, a DC motor only produces a torque at its synchronous speed.
- False Although it can only consume reactive power, a DC machine can produce or consume real power.
- True DC machines require an external electrical connection to their rotor conductors.
- False Provided the breakdown torque is not reached, the speed of a DC motor is not dependent on supply voltage magnitude.
- True When supplied at full rated voltage, a DC machine will typically draw a “starting” current that is many times larger than its rated current.
- False The DC field winding of a DC machine is mounted on the rotor of the machine.

**Problem #34) Multiple Choice – Choose the best response to complete each statement**

- d The field winding of a shunt-excited DC Machine:
- A) is designed to be connected in parallel with the armature
  - B) typically has a relatively large resistance in order to draw a relatively small current
  - C) can be connected in series with a variable external resistor to allow for speed control
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- c A DC motor:
- a) only produces a torque at its synchronous speed
  - b) produces a torque at all speeds except its synchronous speed
  - c) does not have a synchronous speed
  - d) all of the above (a-c) are correct
  - e) none of the above (a-d) are correct

- e** A series-excited DC motor:
- a) produces no starting torque
  - b) generally produces less starting torque than an equivalent rated shunt motor
  - c) can only be self-started if an additional shunt field winding is also applied
  - d) all of the above (a-c) are correct
  - e) none of the above (a-d) are correct

- b** Under normal operation of a DC motor, a decrease in load torque (with no other user supplied changes):
- a) will cause the machine to slow down
  - b) will cause the machine to speed up
  - c) will not change the speed of the machine
  - d) all of the above (a-c) are correct
  - e) none of the above (a-d) are correct

- c** At start-up with applied rated voltage, a shunt excited DC motor:
- a) will draw a starting current equal to the machine's rated current
  - b) will draw a starting current less than the machine's rated current
  - c) will draw a starting current greater than the machine's rated current
  - d) all of the above (a-c) are correct
  - e) none of the above (a-d) are correct

**Problem #35)** Specify whether each statement is **True** or **False**.

**False** A 3- $\Phi$  induction machine develops no torque when rotating faster than its synchronous speed ( $n_r > n_s$ ).

**True** A 3- $\Phi$  induction machine will function as a generator when rotating faster than its synchronous speed ( $n_r > n_s$ ).

**False** 1 lb-ft of torque is equivalent to 746 watts.

**True** Under normal operation, decreasing the field current in a shunt-excited DC motor while maintaining constant terminal voltage will cause in the motor's speed to increase.

**False** A DC machine will function as a generator if it pushed faster than its synchronous speed by an external mechanical source.

**False** When supplied at rated voltage, a 3- $\Phi$  induction machine develops rated torque at its synchronous speed.

**False** A DC machine utilizes a commutator and brushes to provide an external electrical connection to its stator (field) windings.

**False** A permanent-magnet DC motor does not require an electrical connection to its armature.

**True** The voltage " $E_a$ " that appears in the circuit model of a DC machine only exists as a non-zero voltage when the rotor of the machine is rotating.

**False** The "no-load" speed of an "ideal" 3 $\Phi$  induction motor can be increased by increasing the magnitude of its supply voltage.

**True** The "no-load" speed of an "ideal" shunt-excited DC motor can be increased by increasing the magnitude of its supply voltage.

**Problem #36)** Write the letter corresponding to the best response for each statement in the blank preceding the statement.

- E** Given a motor that is supplied with rated voltage and is initially driving a load that requires rated torque, if the load is adjusted such that there is a **50% decrease in the amount of torque required to drive the load**:
- A) the motor will slow down
  - B) the motor will draw more current
  - C) the motor will eventually overheat because it is producing more torque than the load requires
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- B** Given a **DC motor** that is initially operating normally, an **increase in the load torque**
- A) will cause the machine to speed up
  - B) will cause the machine to slow down
  - C) will not change the speed of the machine
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- D** The **relative permeability** of a magnetic core:
- A) must be greater than or equal to one (1)
  - B) will decrease if the core becomes saturated
  - C) would be infinite for an “ideal” magnetic core
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- A** The **Magneto-Motive Force** (MMF) created by a DC current flowing in the source coil of a magnetic circuit:
- A) is proportional to the current flowing in the coil
  - B) is proportional to the rate of change in the voltage applied across the source coil
  - C) may be increased by wrapping the coil around a physically larger magnetic core
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- B** The **field winding** of a **shunt-excited DC motor**:
- A) can also be wired in series with the armature to turn the machine into a series-excited DC motor
  - B) typically has a “high” resistance in order to minimize the electrical power loss in the winding
  - C) requires brushes and a commutator to provide an electrical connection to the winding
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- D** The effective **turns-ratio** of a transformer that is connected to its load in a “step-up” configuration:
- A) will be less than one.
  - B) can be determined by dividing the primary winding’s rated voltage by the secondary winding’s rated voltage.
  - C) will be the inverse of the turns-ratio of the same transformer connected in a “step-down” configuration.
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- C** At **start-up** with applied rated voltage and no external resistances, a **motor** will typically:
- A) draw a starting current that is equal to the machine’s rated current
  - B) draw a starting current that is much less than the machine’s rated current
  - C) draw a starting current that is much greater than the machine’s rated current
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct
- C** Under normal operation, the **series field winding** of a **DC motor**:
- A) can have the number of its turns increased or decreased in order to control the speed of the motor
  - B) may be connected in series with an external, variable resistor to provide a method of speed control
  - C) will have the same current flowing through it that is flowing through the machine’s rotor windings
  - D) all of the above (a-c) are correct
  - E) none of the above (a-d) are correct

### #29 Solution

a) 
$$T_{rated} = \frac{P_{rated} \cdot 5252}{n_{rated}} = \frac{5 \cdot 5252}{1800} = \underline{14.6} \text{ lb} \cdot \text{ft}$$

b) Shunt Excited Motor...

$$I_f = \frac{V_t}{R_f} = \frac{230}{209} = 1.10 \text{ amps} \Rightarrow I_a = I_t - I_f = 14.3 - 1.10 = 13.2 \text{ amps}$$

$$E_a = V_t - I_a \cdot R_a = 230 - (13.2) \cdot (1.5) = 210.2 \text{ volts}$$

$$P_{mech} = E_a \cdot I_a = (210.2) \cdot (13.2) = 2774.6 \text{ watts} \cdot \left(\frac{1 \text{ hp}}{746 \text{ W}}\right) = \underline{3.72} \text{ hp}$$

$$P_{elec} = V_t \cdot I_t = (230) \cdot (14.3) = 3289 \text{ watts}$$

$$\eta = \frac{P_{out}}{P_{in}} = \frac{P_{mech}}{P_{elec}} = \frac{2774.6}{3289} = 0.8436 = \underline{84.36\%}$$

c) At startup  $E_a = 0 \text{ rpm}$  (I.e. – the source “Ea” looks like an ideal wire)...

$$I_f = \frac{V_t}{R_f} = \frac{230}{209} = 1.10 \text{ amps} \quad \text{and} \quad I_a = \frac{V_t}{R_a} = \frac{230}{1.5} = 153.33 \text{ amps}$$

$$I_t = I_f + I_a = 1.10 + 153.33 = 154.43 \text{ amps}$$

### #30 Solution

a) Since Permanent Magnet, there will be no field winding...

$$E_a = V_a - I_a \cdot R_a = V_a - I_a \cdot R_a = 12 - (0.3) \cdot (4) = 10.8 \text{ volts}$$

$$P_{mech} = E_a \cdot I_a = (10.8) \cdot (0.3) = 3.24 \text{ watts} \cdot \left(\frac{1 \text{ hp}}{746 \text{ W}}\right) = 0.004343 \text{ hp}$$

$$T_D = \frac{P_{mech} \cdot 5252}{n_r} = \frac{0.004343 \cdot 5252}{2700} = \underline{0.008448} \text{ lb} \cdot \text{ft}$$

$$\Rightarrow k_G \cdot \phi = \frac{E_a}{n_r} = \frac{10.8}{2700} = 0.004 \text{ V/rpm} \quad k_M \cdot \phi = \frac{T_D}{I_a} = \frac{0.008448}{0.3} = 0.02816 \text{ lb} \cdot \text{ft/A}$$

b) Since Permanent Magnet,  $\phi$  will be constant for both parts... thus  $k_G \cdot \phi$  and  $k_M \cdot \phi$  will also be constant.

$$I_a = 0.5 \text{ amps}$$

$$E_a = V_a - I_a \cdot R_a = V_a - I_a \cdot R_a = 12 - (0.5) \cdot (4) = 10 \text{ volts}$$

∴

$$T_D = k_M \cdot \phi \cdot I_a = (0.02816) \cdot (0.5) = \underline{0.01408} \text{ lb} \cdot \text{ft}$$

$$n_r = \frac{E_a}{k_G \cdot \phi} = \frac{10}{0.004} = \underline{2500} \text{ rpm}$$